Probability theory can be fun and simple with dependent types (Yet another formal theory of probabilities in Coq)

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An overview of existing formalizations of probabilities in Coq<sup>1</sup>

## InfoTheo (2009–ongoing)

• Formalizes *finite probabilities*; used for information theory [Affeldt et al., 2014], error-correcting codes [Affeldt et al., 2020a], robust statistics [Affeldt et al., 2024a]

### coq-proba [Tassarotti, 2023]

• Used to verify a compiler for probabilistic programming languages [Tassarotti and Tristan, 2023]

### FormalML [The FormalML development team, 2023]

• Contains *advanced theorems* in probability theory, e.g., a stochastic approximation theorem [Vajjha et al., 2022]

# A proof engineering effort



Applications of MathComp-Analysis to probabilities?

### MathComp-Analysis timeline

- Asymptotic reasoning + Landau notations → differentiability [Affeldt et al., 2018]
- Lebesgue integral [Affeldt and Cohen, 2023]
- Fundamental theorem of calculus [Affeldt and Stone, 2024]
- <u>Probability theory</u> (2023–ongoing)

# Applications to probabilities

- Verified probabilistic programming languages [CPP 2023, APLAS 2023]
- Verified worst-case failure probability of real-time systems [Markovic et al., 2023]

# Other planned applications

- Verified robust statistics [Daukantas et al., 2021, Affeldt et al., 2024a]
- Verified machine learning [Affeldt et al., 2024b]

# An example: Bernoulli sampling [Rajani, 2019]

### Bernoulli sampling

Given *n* independent 0-1 random variables  $X_i, p \in (0, 1], \theta \in (0, p), \delta \in (0, 1]$ with  $Pr(X_i = 1) = p, X = \sum_{i=1}^n X_i$ , and  $\bar{X} = \frac{X_i}{n}$ , then  $Pr(|\bar{X} - p| \le \theta) \ge 1 - \delta$  when  $n \ge \frac{3}{\theta^2} \ln(\frac{2}{\delta})$ .



# Simple and general: inherit from measure theory with Hierarchy Builder

Definition (Measure) A measure  $\mu : \mathcal{P}(T) \to \overline{\mathbb{R}}$  satisfies: 1.  $\mu(\emptyset) = 0$  (measure-0) 2.  $0 \le \mu(A)$  for any set A (non-negativity) 3.  $\mu(\bigcup_{i=1}^{\infty} A_i) = \sum_{i=1}^{\infty} \mu(A_i)$  ( $\sigma$ -additivity)

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### Definition (Probability measure)

A probability measure additionally implements the following interface:

```
HB.factory Record Measure_isProbability d (T : measurableType d)
  (R : realType) (P : set T -> \bar R) of isMeasure _ _ P :=
  { probability_setT : P setT = 1%E }.
```



# ...and fun: random variables and expectations



 $\texttt{Context } \texttt{d} \ (\texttt{T} \ : \ \texttt{measurableType } \texttt{d}) \ (\texttt{R} \ : \ \texttt{realType}) \ (\texttt{P} \ : \ \texttt{probability } \texttt{T} \ \texttt{R}) \,.$ 

### Definition (Random variables)

A random variable is neither random, nor a variable. It's a measurable function from T to R. Definition random\_variable := {mfun T >-> R}. Notation "{ 'RV' P >-> R }" := (@random\_variable \_ R P).

# ...and fun: random variables and expectations



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### Definition (Expectation)

Expectation of X with the measure P can be expressed as the Lebesgue integral  $\int X \, dP$ : Definition expectation (X : {RV P >-> R}) := \int[P]\_w (X w)%:E.

# **Recovering discreteness**

### Discrete (random) variables

Discrete random variables additionally implement the following interface:

 $\texttt{HB.mixin Record MeasurableFun\_isDiscrete d (T : \texttt{measurableType d}) (R : \texttt{realType})}$ 

 $(X : T \rightarrow R)$  of @MeasurableFun d T R X := { countable\_range : countable (range X) }.

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#### Discrete sums

When X : {dRV P >-> R} (the type of discrete random variables), we build a function  $a_k$  to enumerate its values, and  $c_k$  to enumerate the probabilities, so that the distribution can be written as  $\sum_k c_k \delta_{a_k}$ :

```
Lemma distribution_dRV A : measurable A -> distribution P X A = \sum_{k < 0} c X k * d_a X k A.
```

# (More) formal adventures in convex spaces

[Affeldt et al., 2020b] shows that probability theory benefits from a theory of *convex spaces*. We are porting it to MathComp-Analysis to define convex functions:



```
Convex function
Definition convex_function (R : realType) (D : set R) (f : R -> R) :=
forall t : {i01 R}, {in D &, forall (x y : R), f (x <| t |> y) <= f x <| t |> f y}.
```

### Exponentials are convex

```
Lemma convex_expR : convex_function setT expR.
Lemma convex_powR p : 1 <= p \rightarrow convex_function `[0, +oo[ (fun x : R => powR x p).
```

#### Moments: exponential expectations

Definition mmt\_gen\_fun (X : {RV P >-> R}) (t : R) := 'E\_P[expR X.

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# Applications of convexity: Hölder and Minkowski and $L_p$ -spaces

We are building a theory of  $L_p$  -spaces. For that purpose we prove Hölder's and Minkowski's inequalities, which are also generally applicable to probabilities:

#### Hölder

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(Here \+ and \\* are pointwise addition and multiplication, and N\_p [f] is the p-norm of f)

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#### Hölder

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### Minkowski

(Here \+ and \\* are pointwise addition and multiplication, and N\_p [f] is the p-norm of f)

### More useful lemmas: Markov, Chernoff, Chebyshev and Cantelli

```
Lemma markov (X : {RV P >-> R}) (f : R -> R) (eps : R) : (0 < eps) ->
measurable_fun [set: R] f -> (forall r, 0 <= r -> 0 <= f r) ->
{in Num.nneg &, {homo f : x y / x <= y}} ->
(f eps)%:E * P [set x | eps%:E <= `| (X x)%:E | ] <=
    'E_P[f \o (fun x => `| x |) \o X].
Lemma chernoff (X : {RV P >-> R}) (r a : R) : (0 < r) ->
P [set x | X x >= a] <= mmt_gen_fun X r * (expR (- (r * a)))%:E.
Lemma chebyshev (X : {RV P >-> R}) (eps : R) : (0 < eps) ->
P [set x | (eps <= `| X x - fine ('E_P[X])|) ] <= (eps ^- 2)%:E * 'V_P[X].</pre>
```

```
Lemma cantelli (X : {RV P >-> R}) (lambda : R) :
    P.-integrable setT (EFin \o X) -> P.-integrable setT (EFin \o (X ^+ 2)) ->
    (0 < lambda) ->
    P [set x | lambda%:E <= (X x)%:E - 'E_P[X]] <=
    (fine 'V_P[X] / (fine 'V_P[X] + lambda^2))%:E.</pre>
```

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# Our experiment (WIP): Bernoulli sampling [Rajani, 2019]

#### Theorem

Given *n* independent 0-1 random variables  $X_i$ ,  $p \in (0, 1]$ ,  $\theta \in (0, p)$ ,  $\delta \in (0, 1]$ with  $Pr(X_i = 1) = p$ ,  $X = \sum_{i=1}^n X_i$ , and  $\bar{X} = \frac{X_i}{n}$ , then  $Pr(|\bar{X} - p| \le \theta) \ge 1 - \delta$  when  $n \ge \frac{3}{\theta^2} \ln(\frac{2}{\delta})$ .

#### becomes:

### Conclusions

- We are generalizing Infotheo theories by porting them to MathComp-Analysis (future work: conditional probabilities, information theory, etc.)
- We are working on the verification of probabilistic programs by equational reasoning

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- We aim to have a rich and general library that can be reused
- We are looking for contributors!

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